Alanya Alaaddin Keykubat University | Rafet Kayış Faculty of Engineering **Mechanical Engineering Department** 2023-2024 Fall Semester

Sylla	bus						
Code	/Name	MEC 405 / Control Systems					
Туре		Required					
Credit/ECTS		5/5					
Hour per Week		3 (3+0+0)					
Leve	l/Year	Undergraduate/4					
Seme	ester	Fall					
Class	sroom	WWTh T206 T206 T206					
Content		This course introduces the basic concepts of control theory. Review of Laplace transforms. Dynamic models. System response. Feedback control. Root-locus design. Frequency response design. Introduction to state-space control theory.					
Prer	equisites	MEC 203 Dynamics					
Textbooks		 Primary G Franklin, JD Powell, A Emami-Naeni, Feedback Control of Dynamic Systems, Pearson, 7th Ed., 2015. Supplementary K Ogata, System Dynamics, Pearson, 4th Ed., 2004. RC Dorf, Modern Control Systems, 12th Ed., 2011. 					
Obje	ctives	To design response analysis of a dynamic system					
		 To calculate Laplace transforms for modeling and analyzing linear systems 					
		To formulate dynamic systems using transfer functions					
Cour	se Outcomes	In this course you will be able to:					
		CO2 Apply Laplace transform method in analyzing linear systems					
		CO3 Assemble block diagrams of mechanical systems					
		CO4 Solve transient response analysis problems					
		CO5 Propose automatic controllers					
		C06 Compute response of dynamic systems in the frequency domain					
Wee	kly Schedule of	Topics					
W	Topic						
1	Introduction to analysis and design of dynamic systems						
2	Review of Laplace transform, LTI differential equations						
3	Mathematical modeling of mechanical systems						
4	Dynamic models						
5	Transfer functions, block diagrams						
6	Transfer funct	Transfer functions, response analysis					
7	Electromechar	Electromechanical systems					
8 Transient respo		onse analysis of first and second order systems					

- 9 Time-domain design
- 10 Automatic controllers
- 11 Automatic controllers
- 12 Stability, root-locus

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13 Frequency response design

14 Introduction to state-space approach

Professional
ContributionAbility to model, analyze, and control of mechanical systems

Contribution to Program Outcomes*

	P01	P02	P03	P04	P05	P06	P07	P08	P09	P010	P011
C01	5	3	0	2	0	3	0	2	0	2	0
CO2	4	4	4	3	2	5	3	3	3	4	3
CO3	4	5	4	4	2	4	3	3	2	4	2
CO4	5	5	5	4	2	5	5	4	3	4	2
C05	5	5	5	4	3	5	5	4	3	5	2
C06	5	4	5	4	2	4	4	4	2	4	2

* Contribution Level | 0: None | 1: Very Low | 2: Low | 3: Medium | 4: High | 5: Very High

Special Conditions	• The consequence of violation of the attendance rule is to receive a grade of DZ .						
Requirements	Intermediate knowledge of Matlab						
Course Policy	1. You must attend at least 70% of the sessions including add-drop period.						
	2. Be in the class on time.						
	3. English should always be used to communicate with one another.						
	4. Mobile phones should be switched off and put away during the class.						
	5. You cannot talk to your friends during class no matter what the subject is.						
Cheating & Plagiarism	• Copying or letting someone copy your work on exams, assignments, or reports is cheating.						
	• Cutting and pasting text, figures and tables from web sources or any other electronic source is plagiarism.						
	• The consequence of academic dishonesty is to receive a grade of FF for the course.						
Evaluation	Quizzes (3×10 pts.) 30%						
	Midterm Exam 30%						
	<u>Final Exam 40%</u>						
	Total 100%						

Name/Surname	Akın Oktav	Email	akin.oktav@alanya.edu.tr
Room	209	Office Hours	W 10:30-11:30 Th 16:15-17:15

Prepared by Akın Oktav on August 15, 2023